# Two-Degree-of-Freedom PID Temperature Controllers

## **TN Series**

## INSTRUCTION MANUAL

TCD210227AE

**Autonics** 

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual. other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

Follow Autonics website for the latest information.

## **Safety Considerations**

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- ▲ symbol indicates caution due to special circumstances in which hazards may occur.

⚠ Warning Failure to follow instructions may result in serious injury or death

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
  Failure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

Failure to follow this instruction may result in explosion or fire.

03. Install on a device panel to use.

Failure to follow this instruction may result in electric shock.

04. Do not connect, repair, or inspect the unit while connected to a power

Failure to follow this instruction may result in fire or electric shock.

05. Check 'Connections' before wiring.

Failure to follow this instruction may result in fire.

06. Do not disassemble or modify the unit.

Failure to follow this instruction may result in fire or electric shock.

⚠ Caution Failure to follow instructions may result in injury or product damage

01. When connecting the power input and relay output, use AWG 20 (0.50 mm²) cable or over, and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

Failure to follow this instruction may result in fire or malfunction due to contact failure.

02. Use the unit within the rated specifications.

Failure to follow this instruction may result in fire or product damage

- **03.** Use a dry cloth to clean the unit, and do not use water or organic solvent. Failure to follow this instruction may result in fire or electric shock.
- 04. Keep the product away from metal chip, dust, and wire residue which flow into the unit.

Failure to follow this instruction may result in fire or product damage.

## **Cautions during Use**

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor. For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (TC) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case
  installing power line and input signal line closely, use line filter or varistor at power line
  and shielded wire at input signal line. Do not use near the equipment which generates
  strong magnetic force or high frequency noise.
- Do not apply excessive power when connecting or disconnecting the connectors of the product.

- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
- When changing the input sensor, turn off the power first before changing. After changing the input sensor, modify the value of the corresponding parameter.
- Do not overlapping communication line and power line. Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of external noise.
- Make a required space around the unit for radiation of heat. For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications')
- Altitude Max. 2,000 m
- Pollution degree 2
- Installation category II

## **Ordering Information**

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website .

T N 0 - 2 4 3 4 5 - 6 S - 6	0 - 0 S - 0	6	4	3	4	0	-	0	N	Т
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#### Size

S: DIN W 48 × H 48 mm H: DIN W 48 × H 96 mm

L: DIN W 96 × H 96 mm C: Current

# **2** Control method No mark: Fixed control

P: Program control

#### Alarm outputs

2: Alarm 1/2 4: Alarm 1/2/3/4 6: Alarm 1/2/3/4/5/6

## **②** Control output 1

R: Relay S: SSR drive

C: Current or SSR drive

## **⑤** Control output 2

R: Relay

S: SSR drive C: Current or SSR drive

## **3** Communication

N: None R: RS485

## Option input/output

No.	Digital input CT input		Transmission output
006	0	1	0
800	2	1	0
009	3	1	0
014	3	2	0
026	0	1	1
031	0	2	1
035	6	2	1

## Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals.

Download the manuals from the Autonics website.

## Software

Download the installation file and the manuals from the Autonics website.

#### DAQMaster

DAQMaster is comprehensive device management program. It is available for parameter setting, monitoring.

## **Product Components**

Product

Instruction manual

Bracket

## **Sold Separately**

• Communication converter: SCM Series

- Current transformer (CT)
- Terminal protection cover
- Front cover

## Specifications

**Power supply**  $100 - 240 \text{ VAC} \sim$ ,  $50/60 \text{ Hz} \pm 10\%$ 

ower sup	ply	100 - 240 VAC∼, 50/60 Hz ±10%				
ower con	sumption	≤ 8 VA				
isplay ty	pe	11 segment, LCD type (operating value display part: 7 segment)				
ampling	period	50 / 100 / 250 ms (parameter)				
nput spec	ification	Refer to 'Input Type and Using Range'				
ption	СТ	•0.0-50.0 A (primary current measurement range)     •CT ratio: 1/1,000     •Measurement accuracy: ±5% F.S. ±1digit				
put	Digital	• Contact - ON: ≤ 2 kΩ, OFF: ≥ 90 kΩ • Non contact - residual voltage ≤ 1.0 V, leakage current ≤ 0.1 mA • Outflow current: ≈ 0.5 mA per input				
	Relay	250 VAC~ 3A 1a				
ontrol		12 VDC== ±2 V, ≤ 20 mA				
ontrol utput SSR Current		DC 0 - 20 mA or DC 4 - 20 mA (parameter), Load resistance: $\leq$ 500 $\Omega$				
	Alarm	250 VAC~ 3 A 1a				
ption utput	Transmission	DC 4 - 20 mA (load resistance: $\leq$ 500 $\Omega$ , output accuracy: $\pm 0.3\%$ F.S.)				
	Communication	RS485				
	Туре	ON/OFF, P, PI, PD, PID				
	Multi SV	≤ 4 SV				
ntrol	Group PID	≤ 8 group				
pe	Zone PID	4 zones				
	ARW (Anti Reset Windup)	50 to 200 %				
	Program	≤ 10 patterns				
ogram ntrol	Step	≤ 200 steps (1 pattern: ≤ 20 steps)				
iiciot	Setting type	Time setting				
lysteresis		• Thermocouple, RTD: 1 to 100 (0.1 to 100.0) °C/°F • Analog: 1 to 100 digit				
roportional band (P)		0.1 to 999.9 °C (0.1 to 999.9%)				
tegral tii	me (I)	0 to 9,999 sec				
erivative	time (D)	0 to 9,999 sec				
ontrol cy	rcle (T)	Relay / SSRP output: 0.1 to 120.0 sec Selectable current or SSR drive output: 1.0 to 120.0 sec				
anual re	set	0.0 to 100.0%				
electric	strength	Between the charging part and the case: 3,000 VAC $\sim$ 50/60 Hz for 1 min				
bration		0.75 mm amplitude at frequency of 5 to 55 Hz (for 1 min) in each X Y, Z direction for 2 hours				
elay life	Mechanical	• OUT1/2: ≥ 5,000,000 operations • AL1/2/3/4/5/6: ≥ 20,000,000 operations				
	Electrical resistance	• OUT1/2: ≥ 200,000 operations • AL1/2/3/4/5/6: ≥ 100,000 operations				
Sulation	resistance	≥ 100 MΩ (500 VDC= megger)				
sulation	type	Double insulation or reinforced insulation (mark: $\Box$ , dielectric strength between the measuring input part and the power part: 3 kV)				
oise imm	nunity	$\pm 2\mathrm{kV}$ square shaped noise by noise simulator (pulse width: $1\mathrm{\mu s}$ R-phase, S-phase				
Memory retention		pprox 10 years (non-volatile semiconductor memory type)				
Ambient temperature		-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)				
nbient h	umidity	35 to 85%RH				
Protection structure		IP65 (Front panel, IEC standards)				
ader po	rt	• TNS: top side • TNH, TNL: front side				
cessory		Bracket				
		•TNS: ≈ 128 g (≈ 156 g) •TNH: ≈ 184 g (≈ 286 g)				
nit weigh	ht (packaged)	•TNL: ≈ 301 g (≈ 443 g)				

## Communication Interface

## ■ RS485

Comm. protocol	Modbus RTU/ASCII, Sync-Master, PLC ladderless
Connection type	RS-485, RS-422A
Application standard	EIA RS485 compliance with
Maximum connection	32 units (address: 01 to 99)
Synchronous method	Asynchronous
Comm. Method	Two-wire half duplex
Comm. effective range	≤ 800 m
Comm. speed	≤ 115,200 bps
Response time	5 to 99 ms (default: 20 ms)
Start bit	1 bit (fixed)
Data bit	8 bit (fixed)
Parity bit	None (default), Odd, Even
Stop bit	1 bit, 2 bit (default)
EEPROM life cycle	pprox 1,000,000 operations (Erase / Write)

<sup>• 1</sup> character of ModBus RTU is fixed at 11 bit.

## Input Type and Using Range

The setting range of some parameters is limited when using the decimal point display.

Input type		point	Display	Using range (°C)	Using range (°F)	
	14 (64)	1	KERH	-200 to 1,350	-328 to 2,463	
	K (CA)	0.1	K E R.L	-199.9 to 999.9	-199.9 to 999.9	
	1 (10)	1	JI E.H	-200 to 800	-328 to 1,472	
	J (IC)	0.1	JI C.L	-199.9 to 800.0	-199.9 to 999.9	
	E (CR)	1	E C R.H	-200 to 800	-328 to 1,472	
	E (CR)	0.1	E C R.L	-199.9 to 800.0	-199.9 to 999.9	
	T (CC)	1	E C C.H	-200 to 400	-328 to 752	
	I (CC)	0.1	E C C.L	-199.9 to 400.0	-199.9 to 752.0	
	B (PR)	1	ь РР	0 to 1,800	32 to 3,272	
Thermo	R (PR)	1	R PR	0 to 1,750	32 to 3,182	
-couple	S (PR)	1	5 PR	0 to 1,750	32 to 3,182	
-couple	N (NN)	1	N NN	-200 to 1,300	-328 to 2,372	
	C (TT) 01)	1	[ EE	0 to 2,300	32 to 4,172	
	G (TT) 02)	1	G EE	0 to 2,300	32 to 4,172	
	L (IC)	1	LI E.H	-200 to 900	-328 to 1,652	
	L (IC)	0.1	LI E.L	-199.9 to 900.0	-199.9 to 999.9	
	L (RUS)	1	L R.H	-200 to 800	-328 to 1,472	
	L (RUS)	0.1	L R.L	-199.9 to 800.0	-199.9 to 999.9	
	U (CC)	1	UC C.H	-200 to 400	-328 to 752	
		0.1	U C C.L	-199.9 to 400.0	-199.9 to 752.0	
	Platinel II	1	PLII	0 to 1,390	32 to 2,534	
	Cu50 Ω	0.1	CU 5	-199.9 to 200.0	-199.9 to 392.0	
	Cu100 Ω	0.1	C U 10	-199.9 to 200.0	-199.9 to 392.0	
	JPt100 Ω	1	JPE.H	-200 to 650	-328 to 1,202	
RTD		0.1	JPE.L	-199.9 to 650.0	-199.9 to 999.9	
KID	DPt50 Ω	0.1	dPE5	-199.9 to 600.0	-199.9 to 999.9	
	DPt100 Ω	1	dPt.H	-200 to 650	-328 to 1,202	
	DI (100 12	0.1	dPt.L	-199.9 to 650.0	-199.9 to 999.9	
	Nickel120 Ω	1	N1 15	-80 to 200	-112 to 392	
	0 to 10 V	-	AV I	0 to	10 V	
	0 to 5 V	-	AV 2	0 to	5 V	
Analog	1 to 5 V	-	AV3	1 to 5 V		
Allalog	0 to 100 mV	-	AMV I	0 to	100 mV	
	0 to 20 mA	-	AMA I	0 to	20 mA	
	4 to 20 mA	-	AMA5	4 to	20 mA	
	ine resistance per					

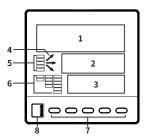
Permissible line resistance per line: ≤ 5 Ω
 O1) C (TT): Same as existing W5 (TT) type sensor
 O2) G (TT): Same as existing W (TT) type sensor

### ■ Display accuracy

Input type	Using temperature	Display accuracy
Thermo -couple RTD	At room temperature (23°C ±5°C)	$ \begin{array}{l} (\text{PV}\pm0.2\% \text{ or }\pm1^\circ\text{C higher one})\pm1\text{-digit} \\ \bullet \text{ Thermocouple K, J, T, N, E below -100^\circ\text{C} and L, U, PLII,} \\ \text{RTD Cu50}\ \Omega, \text{DPt50}\ \Omega: (\text{PV}\pm0.3\% \text{ or }\pm2^\circ\text{C higher one}) \\ \pm1\text{-digit} \\ \bullet \text{Thermocouple C, G and R, S below 200^\circ\text{C}:} \\ (\text{PV}\pm0.3\% \text{ or }\pm3^\circ\text{C higher one})\pm1\text{-digit} \\ \bullet \text{Thermocouple B below 400^\circ\text{C}:} \text{There is no accuracy standards} \\ \end{array} $
	Out of room temperature range	$ \begin{array}{l} (\text{PV}\pm0.5\% \text{ or }\pm2^{\circ}\text{C higher one})\pm1\text{-digit} \\ \bullet \text{RTD Cu50 }\Omega, \text{DPt50 }\Omega; (\text{PV}\pm0.5\% \text{ or }\pm3^{\circ}\text{C higher one}) \\ \pm1\text{-digit} \\ \bullet \text{Thermocouple R, S, B, C, G:} \\ (\text{PV}\pm0.5\% \text{ or }\pm5^{\circ}\text{C higher one})\pm1\text{-digit} \\ \bullet \text{Other sensors: }\leq\pm5^{\circ}\text{C }(\leq\text{-}100^{\circ}\text{C}) \end{array} $
	At room temperature (23°C ±5°C)	±0.2% F.S. ±1-digit
	Out of room temperature range	$\pm 0.5\%$ F.S. $\pm 1$ -digit

## **Unit Descriptions**

- Below is based on TNL Series.
- The shape and function of each part may be different depending on the series, and it is possible to check the additional information in the user manual.



### 1. PV display part (White)

- Setting mode: Displays parameter name
- 2. SV display part (Green)
- 3. Operating value display part (Yellow)
- RUN mode: Displays selected value among MV (Manipulated output value), CT, TIME with unit.
- 4. Temperature control indicator
- Fixed control: Relative PV value status display based on SV
- Program control: Displays temperature control

## 5. Operation status indicator

Display	Name	Description
LOCK	Lock	Turns ON during key lock status.
PROG	Program	Turns ON during program control.
WAIT	Wait	Turns ON during waiting status.
HBA1/2	Heater break alarm	Turns ON when the heater break alarm output is ON.

## 6. Output status indicator

Display	Name	Description
OUT1/2	Control output	Turns ON when the control output is ON
AT	Auto tuning	Flashes during auto tuning every 1 sec
MAN	Manual control	Turns ON during manual control mode
STOP	Control output stop	Turns ON during control output stop mode
HOLD	Program control hold	Turns ON when program control is hold status
AL1 to 6	Alarm output	Turns ON when the alarm output is ON

- RUN mode: Displays PV (Present value) and unit.
- RUN mode: Displays SV (Setting value) and unit. Setting mode: Displays parameter setting value.

- $PV > SV (\nearrow)$ ,  $PV = SV (\rightarrow)$ ,  $PV < SV (\searrow)$
- status of up  $(\nearrow)$ , hold  $(\rightarrow)$ , down  $(\searrow)$ .

7. IIIput key				
Display	Name			
[U]	User key			
[M]	Mode key			
$[\blacktriangleleft], [\blacktriangledown], [\blacktriangle]$	Setting value control key			

#### 8. PC loader port

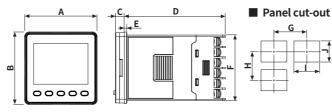
For connecting communication converter (SCM-USP).

## Errors

Display	Input	Description	Output	Troubleshooting
oPEN	Temperature sensor	Flashes at 0.5 sec interval when input sensor is disconnected or sensor is not connected.	'Sensor error, MV' parameter setting value	Check input sensor status.
OFEN	Analog	Flashes at 0.5 sec interval when input is over F.S. $\pm 10\%$ .	'Sensor error, MV' parameter setting value	Check analog input status.
нннн	Temperature sensor	Flashes at 0.5 sec interval if the input value is above the input range.	Heating: 0%, Cooling: 100%	
пппп	Analog	Flashes at 0.5 sec interval if the input value is over 5 to 10% of high limit or low limit value.	Normal output	When input is within the rated
LLLL	Temperature sensor	Flashes at 0.5 sec. interval if the input value is below the input range.	Heating: 100%, Cooling: 0%	input range, this display disappears.
	Analog	Flashes at 0.5 sec interval if the input value is over 5 to 10% of low limit or high limit value.	Normal output	
ERR	-	Flashes at 0.5 sec interval if there is error for setting and it returns to the error-before screen.	-	Check setting method.

## Dimensions

- Unit: mm, For the detailed drawings, follow the Autonics website.
- Below is based on TNS Series.

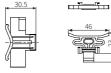


	Body	Body								
	Α	В	С	D	E	F	G	Н	I	J
TNS	49	49	6	69	1.5	44.8	≥ 65	≥ 65	45 <sup>+0.6</sup>	45 <sup>+0.6</sup>
TNH	49	97	6	69	1.5	91.5	≥ 65	≥ 115	45 <sup>+0.6</sup>	92 0 0
TNL	97	97	6	69	1.5	91.5	≥ 115	≥ 115	92+0.8	92+0.8

Other series

## ■ Bracket



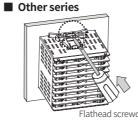




## Installation Method

■ TNS

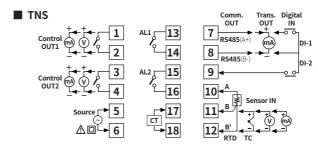


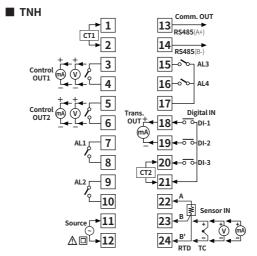


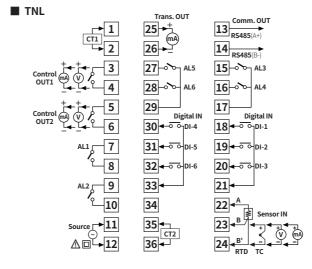
Insert the unit into a panel, fasten the bracket by pushing with tools with a flathead screwdriver.

## Connections

 $\bullet \ \mathsf{Digital} \ \mathsf{input} \ \mathsf{is} \ \mathsf{not} \ \mathsf{electrically} \ \mathsf{insulated} \ \mathsf{from} \ \mathsf{internal} \ \mathsf{circuits}, \mathsf{so} \ \mathsf{it} \ \mathsf{should} \ \mathsf{be} \ \mathsf{insulated}$ when connecting other circuits.







## **Crimp Terminal Specifications**

• Unit: mm, Use the crimp terminal of follow shape





Fork crimp terminal

Round crimp terminal

## Initial Display When Power is ON

When power is supplied, after all display will flash for 1 sec, model name is displayed sequentially. After input sensor type will flash twice, enter into RUN mode.

Display part	1. Model	2. Model	3. Input specification	4. RUN mode
PV	Ł N 5.P	R5	£ YPE	oPEN
SV	42RR	006	K E R.H	0

MO	de Setting							
RUN	Auto before entering to mode (when using password)	$\rightarrow$	Password input	Password	Key input			
				Pass	Auto			
				Fail	$[\blacktriangleleft], [\blacktriangle], [\blacktriangledown]$			
					[MODE]	Run mode		
	[◀], [▲], [▼] (in manual control)	$\rightarrow$	MV setting	Move digits: [◀] Change value: [▲], [▼] Save: [MODE] or no key input over 3 sec			$\bigcap$	
	[◀], [▲], [▼] (in auto control)	$\rightarrow$	SV setting					
	[ <b>▼</b> ] + [ <b>▲</b> ] 3 sec	$\rightarrow$	Control output run/stop	Auto	→			
	[M] + [ <b>A</b> ]	$\rightarrow$	Operating value display part (MV/CT/TIME) setting	Auto		$\rightarrow$	RUN	
	[U] + [◀] / [▼] / [▲] 2 sec	$\rightarrow$	Shortcut key 1/2/3	Auto		$\rightarrow$		
	[ <b>◀</b> ] + [ <b>▼</b> ] 3 sec	$\rightarrow$	Key lock	[ <b>◄</b> ] + [ <b>▼</b> ] 3	3 sec	$\rightarrow$		
	[M] 2 sec	$\rightarrow$	Parameter group	[ <b>◀</b> ] 2 sec		$\rightarrow$		
	[U] 2 sec	$\rightarrow$	User customized parameter group	[U]		$\rightarrow$		
	[ <b>◄</b> ] + [ <b>▲</b> ] + [ <b>▼</b> ] 5 sec	$\rightarrow$	Parameter reset	Auto		$\rightarrow$		

<sup>•</sup> TNS series does not support 'MV setting', 'Operation value display part setting' mode. For the details, refer to the

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